

## Phys141 – Fri 11/11

TODAY: Oscillations (Ch 15) + Waves (Ch 16)

## Harmonic oscillation

Harmonic oscillation  $\frac{d^2\theta}{dt^2} = -\omega^2\theta$  Show that the ansatz solves the equation  $\theta = \theta_{\max} \cos(\omega t + \phi)$

### FEATURES:

$\omega$ : angular frequency – related quantities are:

$$f = \omega/2\pi \quad \text{frequency of oscillation}$$

$$T = 1/f \quad \text{Period of oscillation}$$

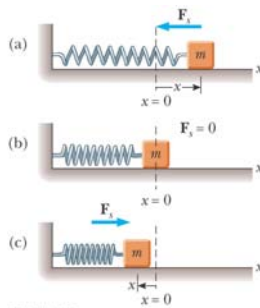
$\theta_{\max}$ : Amplitude of oscillation

$\phi$ : phase constant or the initial phase angle

## Example 2: Spring-Mass System

A block of mass  $m$  is attached to a spring, the block is free to move on a frictionless horizontal surface

When the spring is neither stretched nor compressed, the block is at the **equilibrium position**  $x = 0$



Note: Force pointed toward equilibrium position

## Simple Harmonic Motion

The force described by Hooke's Law is the net force in Newton's Second Law

$$F_{\text{Hooke}} = F_{\text{Newton}}$$

$$-kx = ma_x$$

Acceleration

$$a_x = \frac{d^2x}{dt^2} = -\frac{k}{m}x$$

$$\omega^2 = \frac{k}{m} \quad \left\{ \begin{array}{l} \frac{d^2x}{dt^2} = -\omega^2x \end{array} \right.$$

Which function satisfies this differential equation?

## Simple harmonic motion

$$x(t) = A \cos(\omega t + \phi)$$

$A, \omega, \phi$  are all constants

$A$  amplitude of the motion

$\omega$  angular frequency  $\omega = \sqrt{\frac{k}{m}}$

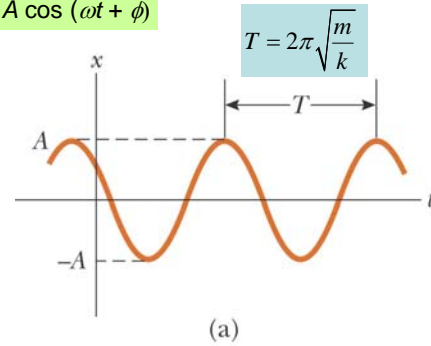
frequency  $f = \frac{1}{T} = \frac{\omega}{2\pi}$

Period  $T = 2\pi \sqrt{\frac{m}{k}}$

$\phi$  phase constant or the initial phase angle

## Graphical Representation

$$x(t) = A \cos(\omega t + \phi)$$



When is max amplitude reached?

$$\rightarrow \cos(\omega t + \phi) = 1 \rightarrow \omega t + \phi = 0, 2\pi, 4\pi, 6\pi, \dots$$

Phase constant (initial phase angle) determined by initial conditions

## Damped Oscillation

In many real systems, energy is dissipated into heat (e.g. due to viscosity) i.e. non-conservative forces are present:

**Viscous force:**  $R = -b v = -b \frac{dx}{dt}$   
 -  $b$  is called the **damping coefficient**



Spring oscillation without viscous force

$$m a_x = m \frac{d^2 x}{dt^2} = -kx$$

With viscous force

$$m \frac{d^2 x}{dt^2} = -kx - b \frac{dx}{dt}$$

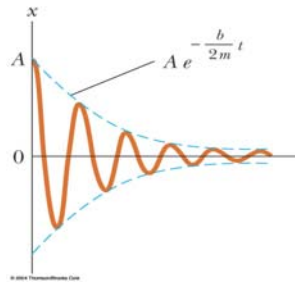
## Damped Oscillation, equations

For small  $b$ , the equation can be solved as:

$$x(t) = A e^{-\frac{b}{2m}t} \cos(\omega t + \phi)$$

The angular frequency will be smaller than without the retardation

$$\omega = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

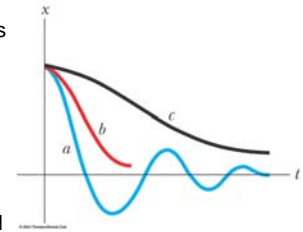


## Types of Damping

• Graphs of position versus time for

- (a) an underdamped oscillator
- (b) a critically damped oscillator
- (c) an overdamped oscillator

• For critically damped and overdamped there is no angular frequency

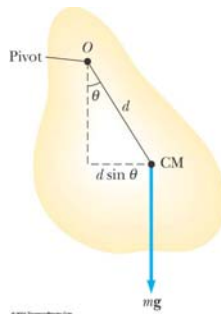


Has to be  $> 0$  for oscillations

$$\omega = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

## Physical Pendulum

- Mass NOT concentrated in one point
- The gravitational force provides a torque about an axis through  $O$
- The magnitude of the torque is  $mgd \sin \theta$
- $I$  is the moment of inertia about the axis through  $O$



## Physical Pendulum

From Newton's Second Law (torque version)

$$-mgd \sin \theta = I \frac{d^2 \theta}{dt^2}$$

Note: The gravitational force produces a restoring force  
Assuming  $\theta$  is small, this becomes

$$\frac{d^2 \theta}{dt^2} = -\left(\frac{mgd}{I}\right)\theta = -\omega^2 \theta \quad \rightarrow \quad \omega = \sqrt{\frac{mgd}{I}}$$

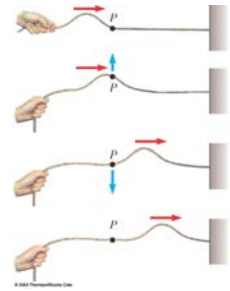
-> A physical pendulum can be used to measure the moment of inertia of a flat rigid object

## Chapter 16 - Waves

- There are two main types of waves
  - Mechanical waves
    - Some physical medium is being disturbed
    - The wave is the propagation of a disturbance through a medium
  - Electromagnetic waves (next semester)
    - No medium required
    - Examples are light, radio waves, x-rays

## Example: Pulse on a Rope

- flick one end of a rope under tension
- A single bump is formed and travels along the rope
  - The bump is called a **pulse**

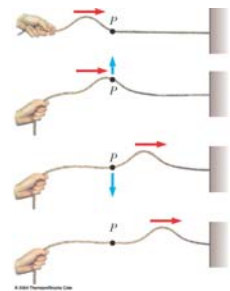


## Pulses and Waves

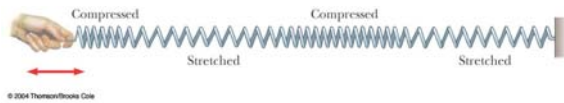
- rope is the “medium” through which **pulse** travels
- The pulse has a definite speed of propagation along the medium
- A continuous flicking of the rope would produce a periodic disturbance which would form a **wave**
- Waves/ pulses
  - transfer energy over a distance
  - Matter is **not** transferred over a distance

## Transverse Wave

- A traveling wave or pulse that causes the elements of the disturbed medium to move **perpendicular** to the direction of propagation is called a **transverse wave**
- particle motion
  - > blue arrow
- propagation direction
  - > red arrow

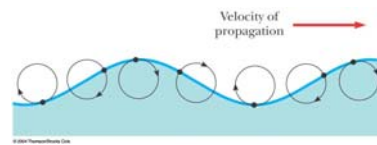


## Longitudinal Wave



- A traveling wave or pulse that causes the elements of the disturbed medium to move parallel to the direction of propagation is called a **longitudinal wave**
- The displacement of the coils is parallel to the propagation

## Complex Waves



- Some waves exhibit a combination of transverse and longitudinal waves
- Surface water waves are an example